

Uncertainty Estimation in the Sphygmomanometers Calibration according to OIML R16-1 from a Legal Metrology Perspective

Estimación de la incertidumbre en la calibración de esfigmomanómetros según OIML R16-1 desde una perspectiva de metrología legal

Submitted on: June 29, 2019 | Accepted on: October 22, 2020 | Published: October 11, 2021

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DOI: https://doi.org/10.11144/javeriana.iued25.uesc

How to cite this article:

A. F. Ramírez-Barrera, E. Delgado-Trejos, and V. Ramírez-Gómez, "Uncertainty estimation in the sphygmomanometers calibration according to OIML R16-1 from a legal metrology perspective," *Ing. Univ.*, vol. 25, 2021. https://doi.org/10.11144/Javeriana.iued25.uesc

Abstract

Objective: To estimate the uncertainty in the calibration of sphygmomanometers according to OIML R16-1 from a legal metrology perspective. Materials and methods: Four (4) sphygmomanometers of different brands with a resolution of 2 mmHg were selected to perform the calibration, using several direct comparisons between a sphygmomanometer and a digital standard manometer with a resolution of 0.01 mmHg, generating pressure with a pneumatic clamp. The uncertainty was estimated using the Guide to the Expression of Uncertainty in Measurement (GUM) and the OIML R16-1 international recommendation. Two measurement series were computed, each with upward and decent sequence, to achieve 4 measurements each time with the corresponding errors. Results and discussion: Several uncertainty representations were achieved, in particular expressions such as type A, type B, and expanded, employing a physic modeling and a non-stochastic mathematic model. From the sphygmomanometer measurement series in processes, the uncertainty calibration contributions were analyzed, finding that the dominant uncertainty source, in most cases, is derived from the equipment resolution, followed by repeatability and hysteresis in the sphygmomanometer test processes. Conclusions: The proposed structure for estimating uncertainty follows international regulations and can be used in procedures for approval of models with a final impact on patient safety.

Keywords:legalmetrology,sphygmomanometers,measurementuncertainty.

Resumen

Objetivo: Estimar la incertidumbre en la calibración de esfigmomanómetros bajo la OIML R16-1 desde una perspectiva de metrología legal. Materiales y métodos: Se seleccionaron aleatoriamente cuatro (4) esfigmomanómetros de diferentes marcas con resolución de 2 mmHg para realizar la calibración, la cual consiste en realizar comparaciones directas entre e1 esfigmomanómetro y un manómetro patrón digital con resolución de 0,01 mmHg, generando presión por medio de una pinza neumática. La incertidumbre se estima usando la Guía para la Expresión de la Incertidumbre de Medida (GUM) y la recomendación internacional OIML R16-1, mediante dos series de mediciones, cada una con secuencia ascendente y descendente, para obtener en cada caso 4 mediciones con su error correspondiente. Resultados y discusión: Se obtiene la representación de la incertidumbre en sus expresiones tipo A, tipo B y expandida, por medio de un modelado físico y matemático no estocástico. De las series de mediciones obtenidas del esfigmomanómetro en los procesos de calibración, se analizan los aportes obtenidos de incertidumbre, donde se infiere que la incertidumbre predominante, en la mayoría de los casos, es por resolución del equipo, seguido del comportamiento del equipo en la prueba de repetibilidad e Conclusiones: histéresis. La estructura estimación la propuesta para de la incertidumbre sigue los lineamientos internacionales y puede usarse también en procesos de aprobación de modelo para un impacto final en la seguridad del paciente.

Palabrasclave:metrologíalegal,esfigmomanómetro,incertidumbredemedición.

Introduction

Activities aimed at patient safety using medical technology are becoming increasingly important. Consequently, high-use clinical diagnostic equipment such as sphygmomanometers, which provide relevant information for decision-making in the medical care part, should be taken as objects of primary care study [1]. Thus, different National Institutes of Metrology have increased studies on the application of metrology in health through legal metrological control.

The Institute of Metrology of Bosnia and Herzegovina (IMBIH) [2] highlighted the need to introduce metrology in clinical medicine, particularly in the standardization of norms associated with the inspection of medical devices, which provides a basis for the introduction of these devices in the legal metrology system and allows the measurement units to be linked with a precise definition in terms of ranges and errors. However, they did not report a deep and specific approach to estimate uncertainty for the particular case of medical equipment. Likewise, a study in Portugal discussed the role of metrology in medical devices, with other activities that the European Union has been advancing in this area, showing that after marketing and commissioning, there is no additional regulated metrological control for most medical devices [3]. Consequently, the study highlighted the importance of generating models to estimate uncertainty in medical equipment and greater urgency in high use in clinical practice, such as sphygmomanometers. In this same sense, the National Institute of Metrology, Quality and Technology (INMETRO) of Brazil has developed regulations that delegate powers to a network of competent state institutes to carry out the mandatory verification of medical equipment used for weighing adults, pediatric scales, and sphygmomanometers [4]. It is reported that the lack of metrological control or verification, as well as the inadequate frequency of verification of these instruments, are generally the cause of measurement errors, followed by an erroneous or inadequate diagnosis, which puts the well-being of the patient at risk. In another work [5], it is reported that INMETRO uses a system to perform periodic verifications of measuring instruments, pointing to a legal metrological control where the model approval processes as recommended by OIML R16-1, show the absence of the estimate. uncertainty for the case of sphygmomanometers. Likewise, in Colombia there have been notable changes with respect to the standards aimed at technological management applicable to medical equipment, with a focus on legal metrological control, for which reason research on management models that integrate the requirements of the legal metrological control applied to biomedical equipment, and with the measurement processes involved in conformity assessment to support activities aimed at patient safety [6]. Other investigations [1] have focused on using statistical techniques to compare blood pressure measurements obtained with a radial sphygmomanometer with those obtained with two other types of non-invasive sphygmomanometers. In contrast, other studies [7] focus on the implications of errors in the calibration of sphygmomanometers in primary care. However, these investigations highlighting the importance of the measurement results do not direct their attention to the uncertainty estimation models for this type of equipment.

The International Organization of Legal Metrology (OIML) issued the international recommendation OIML R16-1 "Non-invasive mechanical sphygmomanometers" with specifications on general requirements, performance, efficiency, and mechanical and electrical safety, including test methods for type approval, applicable both to non-invasive mechanical sphygmomanometers, as well as their accessories that facilitate the non-invasive measurement of blood pressure using an inflatable cuff [8]. However, the metrological requirements section does not specify the estimation of uncertainty during the sphygmomanometer calibration process. In [9], a more effective approach for the legal metrological control of sphygmomanometers is presented, as established in OIML R-16: 2002, with a proposal to estimate uncertainty. However, not all sources are considered, which can affect the measurement in the calibration process.

This article presents a procedure based on the physical and mathematical model for estimating uncertainty, aiming to cover the need to know more precisely the measurement process of sphygmomanometers by proposing a structure with an approximation to the different sources that send the non-invasive blood pressure calibration process. We use the non-stochastic methodology called Guide to the Expression of Uncertainty in Measurement (GUM), and we take what is established in the international recommendation OIML R16-1 as a principle.

Materials and methods

In addition to exposing the materials and methods used to perform the calibration of the sphygmomanometer, we also include the method used to propose the estimation of uncertainty as established in the Guide to the Expression of Uncertainty in Measurement (GUM), which is based on the international recommendation OIML R16-1: 2002 [8].

Technical specifications

To perform the calibration, a generic description of the operation is used through direct comparison as a measurement method [10], obtained by observing directly in an instrument under test compared by a measurement instrument designed to measure magnitudes of the same nature as a reference [11]. For this calibration, the indication of the sphygmomanometer is used, compared with a reference manometer used as a standard, which, in metrological terms, has better technical specifications, which allows it to be selected as a reference

standard, based on what is established in the OIML R- 16: 2002 [8]. To perform the data collection exercise and compare the results obtained, four (4) sphygmomanometers of different brands were randomly selected with previous calibrations every six months and have not been repaired.

Before starting the measurement process, and per the provisions of OIML R 16-1: 2002 [8], an air leak test of the pneumatic system must be performed. It is established that such a test must be carried out over the entire measurement range of the instrument under test, at at least five equidistant pressure points (for example, 7 kPa (50 mmHg), 13 kPa (100 mmHg), 20 kPa (150mmHg), 27kPa (200mmHg) and 34kPa (250mmHg)); allowing each value to stabilize. The leakage should not exceed 0.5 kPa / min (4 mmHg / min), if the instrument exceeds the maximum error allowed in the leak test, this should be recorded, and the equipment rejected. Additionally, an inspection of the zero must be carried out, where it is identified if the instrument has zero, as shown in figure 1. If so, the measurement of this is carried out. This measurement's maximum permissible error must not exceed \pm 0.4 kPa (\pm 3 mmHg); otherwise, only visual inspection is carried out, and a record must be left.





Source: OIML R 16-1, 2002

To perform the calibration through direct comparison and as established in the OIML R 16-1: 2002 recommendation [8], a calibrated reference manometer must be available, and the expanded uncertainty of the calibration certificate must be less than ± 0.1 kPa (± 0.8 mmHg), plus a pneumatic pump that generates a pressure of up to 4136 kPa (600 psi). The following reference manometer and pneumatic pump were used to take measurements in this research, as established in table 1.

Table 1. Materials						
Instrument	Technical specifications					
	Resolution: 0.01 mmHg					
Reference manometer	Accuracy: $\pm 0.025\%$ rdg					
	Certified uncertainty: ± 0.062 mmHg, k= 1.99					
Pneumatic gripper	Pressure range: 0 kPa (0 mmHg) a 4136 kPa (31022.55 mmHg)					
Rigid container	Rigid 500 ml container. Replace the human arm inside the sphygmomanometer					

Source: own work

Table 2. Equipment under test						
Instrument Resolution						
Sphygmomanometer 1	2 mmHg					
Sphygmomanometer 2	2 mmHg					
Sphygmomanometer 3	2 mmHg					
Sphygmomanometer 4	2 mmHg					
Source: own work						

Complementary to the materials described in table 1 and table 2, some auxiliary materials, and tools such as connectors and conduction hoses are used to make the connections between the instruments; a stopwatch to perform the leak tests and the calibration process; and a rigid structure, to eliminate the difference in heights between the sphygmomanometer and the reference manometer.

Environmental conditions and permitted ranges

It is necessary to measure the temperature and relative humidity of the place where the calibration is carried out to confirm that this place does not exceed the temperature and humidity conditions described in this section. Therefore, it is necessary to have a traceable thermo-hygrometer that can measure environmental conditions during calibration. Additionally, the thermo-hygrometer must take the maximum value and the minimum value obtained during the process, and these data must be recorded. Similarly, the laboratory facilities' environmental conditions where the standard equipment is guarded must be taken, bearing in mind the permitted ranges as established in table 3.

Table 3. Temperature and relative humidity				
Magnitude	Operating range			
Temperature	15 °C a 25 °C			
Relative humidity	20 %hr a 85 %hr			
Source: OIML R 16-1, 2002				

Consequently, the maximum allowed error criteria must be met at the time of the measurements, as established in table 4.

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Table 4. Ranges for maximum permissible errors							
Equipment type Maximum permissible error							
New	± 0.4 kPa o ± 3 mmHg						
Used	± 0.5 kPa o ± 4 mmHg						
Source: OIML R 16-1, 2002							

It is also important to consider the work reported in [9], in which the OIML R 16-1 is analyzed in detail. It is proposed to be established as a criterion for evaluating the conformity of equipment the imposition of a safety margin less than or equal to 30% of the tolerance interval [12], which for the legal metrological control applied to sphygmomanometers would correspond to 2.7 mmHg, as this value is associated with 30% of the difference between the maximum and minimum values of the diastolic pressure of the prehypertension.

Calibration method

The sphygmomanometer and the reference manometer are fixed in the rigid structure as shown in figure 2, the above to eliminate the uncertainty due to the difference in heights.



Figure 2. Sphygmomanometer calibration setup

Source: own work

The thermal balance between the sphygmomanometer, the reference manometer, and the environment must be monitored for 20 minutes until the environmental conditions stabilize in the intervals described in table 3. If it does not stabilize, the calibration cannot be performed. If these conditions are exceeded during the calibration, the calibration must be stopped and wait for the conditions to stabilize. When this happens, the calibration is started from zero. If, on the contrary, the conditions do not stabilize, it must be suspended. Subsequently, pre-charges must be performed to excite the system of the equipment under

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test at 50% and 90% or 100% of the scale, in addition to performing an air leak test as previously described in the technical specifications to do so, which should set the value to be measured on the standard instrument and count the time of the leak with the stopwatch. The leakage should not exceed 0.5 kPa / min (4 mmHg / min); If the instrument under test exceeds the maximum permissible error in the leak test, this should be recorded and rejected.

The measurement points are selected in intervals no greater than 7 kPa (50 mmHg), between 0 kPa (0 mmHg) and the maximum value of the sphygmomanometer scale, where the value that will be measured in the instrument underneath must first be set and then read the data on the reference manometer. After that, the first series' data are taken in ascending order, and the observed values are recorded. To start the downward measurement of the first series, wait 1 minute at the maximum point of the equipment and record the data. Next, the next descending point is taken and so on until series 1 is completed. It takes 1 minute at the end of the data collection of series 1 and we begin again with the second series in an ascending manner [13].

Physical and mathematical model for estimating uncertainty

The physical measurement model consists of assumptions about the measurand itself and the relevant physical and chemical variables for the measurement. However simple it may be, a physical measurement has a model associated with it that only approximates the real process [14]. In this article, the physical and mathematical model was based on the phenomenon generated by the dynamic pressure in a sphygmomanometer, represented in the following equation.

$$E = Y_R - \overline{Y}_i + u(Uncert.Type A) + u_B(Uncert.Res) + u_B(Pat.Acc)$$
(1)
+ u_B(Uncert.His) + u_B(Pat.Cal)

Where

Ε	:	Absolute error of the instrument under test
Y_R	:	Reference value
$\overline{Y_{\iota}}$:	Average of the instrument readings
u(Uncort Tama A)		Standard deviation of the data, divided by the total number of
u(Uncert.Type A)		measurements taken
$u_B(Uncert.Res)$:	Resolution of the instrument under test
$u_B(Pat.Acc)$:	Accuracy of the standard equipment
$u_B(Uncert.His)$:	Hysteresis of the instrument under test
(Dat Cal)		Value extracted from the calibration certificate of the standard
$u_B(Pat. Cal)$		instrument

For the mathematical calculation of uncertainty, as specified by the GUM, it must be categorized as random sources (type A uncertainty) and systematic (type B uncertainty). The purpose of the classification in types A and B is to indicate two different ways of evaluating the uncertainty components. Type A components are expressed by estimated variances Si^2 (or the estimated "standard deviations" S_i), and the number of degrees of freedom v_i , where necessary, will be given the covariances. The components of type B must be expressed through estimated variances uj^2 , which can be considered approximations to the corresponding variances, whose existence is assumed. The quantities uj^2 can be treated as variances and the u_j as standard deviations. When necessary, covariances should be treated similarly [15]. In figure 3, the different sources in which the proposal for the estimation of the expanded uncertainty are composed are exposed, bearing in mind the physical phenomenon for sphygmomanometers' calibration.





Source: own work

Considering the above, equations (2) and (3) represent the determination of the type A uncertainty by the repeatability of the measurements.

$$S_{(I)} = \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (I_{ii} - \bar{I})^2}$$
⁽²⁾

$$u_A = \frac{S_{(I)}}{\sqrt{n}} \tag{3}$$

Where

n	:	Total number of measurements taken.
I _{ii}	:	It is each of the registered standard readings.
Ī:	:	Average of the readings.
$S_{(I)}$:	Standard deviation of the data.
u_A :	:	Type A uncertainty, due to data variation.

We analyzed how the different instruments and the physical phenomenon intervene in the measurement system to determine the various type B uncertainty sources, ascertaining the systematic components presented in table 5.

Standard uncertainty	Formula		Parameter
Resolution of the instrument under test	$u_{B(Uncert.Res)} = \frac{Instrument\ resolution}{\sqrt{3}}$	(4)	$u_{B(Uncert.Res)}$: Type B uncertainty associated with the resolution of the instrument. Instrument resolution: The smallest difference in indication of a display device that can be significantly perceived [11]
Hysteresis	$u_{B(Uncert.His)} = \frac{E_{\downarrow} - E_{\uparrow}}{\sqrt{12}}$	(5)	$u_{B(Uncert.His)}: \text{ Type B uncertainty} associated with the hysteresis of the instrument.}$ $E_{\downarrow}: \text{ Descending data.}$ $E_{\bullet}: \text{ Ascending data}$
Standard instrument accuracy	$u_{B(Pat.Acc)} = rac{Instrument\ accuracy}{\sqrt{3}}$	(6)	$u_{B(Pat.Acc)}$: Type B uncertainty associated with the accuracy of the standard instrument. <i>Instrument accuracy</i> : It is the maximum permissible error of the standard equipment.
Calibration certificate of the standard instrument	$u_{B(Pat.Cal)} = \frac{U_e}{k}$	(7)	$u_{B(Pat.Cal)}$: Type B uncertainty associated with the calibration certificate of the standard instrument. U_e : It is the expanded uncertainty indicated in the calibration certificate of the standard instrument. k: It is the coverage factor expressed in the calibration certificate of the standard instrument.
	Source: own w	/ork	

Table 5. Components of Type B uncertainty

Consequently, the sensitivity coefficients, which describe how sensitive the measurand is regarding the corresponding input magnitude variations, must be calculated. In other words, it is expressed as the output estimate and varies with changes in the input estimates $x_1, x_2, ..., x_N$ [15]. As there is a functional relationship through a mathematical model for the measurand $y = f(x_1, x_2, ..., x_N)$, for this investigation, the sensitivity coefficient c_i can be estimated by the partial derivative of f regarding x_i ,

$$c_i = \frac{\partial f(x_1, x_2, \dots, x_N)}{\partial x_i} \tag{8}$$

And according to the law of propagation of uncertainties, the expression for the combined standard uncertainty $u_c(E)$ (it is assumed that there is no correlation between the variables) is:

$$u_{c}^{2}(E) = \sum_{i=1}^{N} \left[\frac{\partial f}{\partial x_{i}} \right]^{2} \times u^{2}(xi) = \sum_{i=1}^{N} [c_{i}u(xi)]^{2} \equiv \sum_{i=1}^{N} u_{i}^{2}(E)$$
⁽⁹⁾

When applying equations (8) and (9) to the sphygmomanometer calibration process and considering both the sources of uncertainty and the mathematical model expressed in equation (1), we obtain equation (10).

$$u_{c}(E) = \left(\left(u_{A} * \frac{\partial(fE)}{\partial(Tipo A)} \right)^{2} + \left(u_{B(Uncert.Res)} * \frac{\partial(fE)}{\partial(Uncert.Res)} \right)^{2} + \left(u_{B(Uncert.His)} * \frac{\partial(fE)}{\partial(Uncert.His)} \right)^{2} + \left(u_{B(Pat.Acc)} * \frac{\partial(fE)}{\partial(Pat.Acc)} \right)^{2} + \left(u_{B(Pat.Cal)} * \frac{\partial(fE)}{\partial(Pat.Cal)} \right)^{2} \right)^{2}$$

The estimate of the effective degrees of freedom of the standard uncertainty $\mu_c(y)$ associated with the output estimate is obtained using the Welch-Satterthwaite formula.

$$V_{eff} = \frac{u_c^4(E)}{\sum_{i=1}^{N} \frac{u_i^4(E)}{v_i}}$$
(11)

$$V_{eff} = \frac{\mu_c^4(E)}{\sum_{i=1}^{N} \frac{u_A^4}{n-1} + \frac{u_B^4(Uncert.Res)^{+u_B^4}(Uncert.His)^{+u_B^4(Pat.Acc)^{+u_B^4(Pat.Cal)}}{v}}{(12)}$$

After applying equation (12), once the effective value V_{eff} has been obtained, this value must be compared in the Student t distribution table to obtain the coverage factor (k) evaluated for a coverage probability of 95.45%, which must be multiplied by the combined uncertainty ($\mu_c(E)$) to estimate the result of the expanded uncertainty with equation (13).

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$$U_e = u_c(E) * k \tag{13}$$

Where

 U_e :Expanded uncertainty $u_c(E)$:Combined uncertaintyk:Coverage factor

Finally, one of the results obtained in this research was the proposed methodology for estimating the uncertainty in the calibration of sphygmomanometers under OIML R16-1 from a legal metrology perspective using the GUM method, as presented in figure 4.

Define the measurand (E) Eq. 1 ٠ Establish the physical and mathematical Ea. 1 model Select standard instrument and equipment Tab. 3 under test according to OIML R16-1 Where: . Tab: Table Identify sources of uncertainty Tab. 4 Eq: Equation * Taking measurements Tab. 5 ŧ Reduce: Get the standard uncertainty Tab. 4 Eq. 3 Calculate the combined standard Eq. 10 uncertainty * Eq. 10 Estimate correlations ٠ Choose confidence level Eq. 12 Quantify the number of Eq. 12 degrees of freedom? Estimate the degrees of freedom . Calculate the effective number of degrees of freedom * Compare with the t-Student Conservatively determine coverage distribution table factor k = 2Calculate the expanded uncertainty U., Eq. 13 ŧ END

Figure 4. Schematic diagram for estimating the uncertainty using the GUM method

Results

The estimation of uncertainty in the calibration is proposed according to what is established in a non-stochastic methodology such as the Guide to the Expression of Uncertainty in Measurement (GUM) [15]. This has been used in different processes from analytical chemistry tests [16], gamma-ray spectrometry [17], as well as in the application in measuring instruments such as electromagnetic compatibility tests [18].

Estimation of uncertainty in sphygmomanometers

Measurements were taken as proposed in the method presented above, and the results are presented in the following tables. For each of the exercises, two series of ascending and descending sequences were performed. Finally, four (4) measurements were obtained, and the measurement error was calculated for each of the points. The measurement method and the points selected to carry out the calibration process were taken according to the laboratory experience, bearing in mind that the points encompass the physiological behavior of blood pressure since it includes points from healthy, hypertensive, or hypotensive patients. The number of points was considered according to the guidelines defined in DKD-R 6-1 [13], where it is established to perform the calibration in two sequences for each point (2 ascending and 2 descending) and at the maximum point of the equipment.

	· · ·						
Deferrerenter		Series 1		Ser	ies 2	A	Eman
Kelerenc	e value	Sequence	Sequence	Sequence	Sequence	Average	EITOI
		M1 (Asc)	M2 (Desc)	M3 (Asc)	M4 (Desc)		
Pa	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg
5332.90	40	40.36	39.42	40.32	39.40	39.875	0.125
7999.34	60	60.57	59.63	60.56	59.59	60.088	-0.088
10665.79	80	80.50	79.73	80.55	79.70	80.120	-0.120
13332.24	100	100.95	99.54	100.93	99.52	100.235	-0.235
15998.69	120	120.84	119.38	120.80	119.35	120.093	-0.093
21331.58	160	159.75	158.29	159.70	158.30	159.010	0.990
26664.48	200	199.40	198.20	199.37	198.21	198.795	1.205
33330.60	250	248.68	248.28	248.24	248.24	248.360	1.640
39996.72	300	299.48	298.90	299.43	298.87	299.170	0.830

Table 6. Measurement data of a sphygmomanometer 1

D . f		Series 1		Ser	ies 2	- A womo go	D
Kelefenc	e value	Sequence	Sequence	Sequence	Sequence	Average	LITOI
		M1 (Asc)	M2 (Desc)	M3 (Asc)	M4 (Desc)		
Pa	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg
5332.90	40	40.04	40.13	40.27	40.27	40.178	-0.178
7999.34	60	60.88	60.76	60.87	60.79	60.825	-0.825
10665.79	80	80.85	80.58	80.87	80.82	80.780	-0.780
13332.24	100	100.75	100.58	100.82	100.73	100.720	-0.720
15998.69	120	120.83	120.88	120.74	120.32	120.693	-0.693
21331.58	160	160.71	160.62	160.44	160.28	160.513	-0.513
26664.48	200	200.59	200.43	200.49	200.10	200.403	-0.403
33330.60	250	250.26	250.16	250.21	250.03	250.165	-0.165
39996.72	300	300.24	300.24	300.09	300.12	300.173	-0.173
			•				

Table 4. Measurement data of a sphygmomanometer 2

Source: own work

Table 5. Measurement data of a sphygmomanometer 3

Reference value		Series 1		Ser	ries 2	Avorago	Free
		Sequence	Sequence	Sequence	Sequence	Average	LIIUI
		M1 (Asc)	M2 (Desc)	M3 (Asc)	M4 (Desc)		
Pa	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg
5332.90	40	41.27	41.49	41.22	41.47	41.363	-1.363
7999.34	60	61.72	61.57	61.67	61.53	61.623	-1.623
10665.79	80	81.82	81.54	81.74	81.51	81.653	-1.653
13332.24	100	102.22	101.37	102.22	101.32	101.783	-1.783
15998.69	120	121.70	120.92	121.66	120.83	121.278	-1.278
21331.58	160	161.12	160.83	161.12	160.76	160.958	-0.958
26664.48	200	200.44	200.83	200.36	200.74	200.593	-0.593
33330.60	250	250.45	250.43	250.46	250.49	250.458	-0.458
39996.72	300	300.82	300.62	300.74	300.66	300.710	-0.710

Source: own work

Table 9. Measurement data of a sphygmomanometer 4

Defener ee velve		Ser	ies 1	Ser	ries 2	Avonogo	Ennon
Kelerenc	e value	Sequence	Sequence	Sequence	Sequence	Average	LIIOI
		M1 (Asc)	M2 (Desc)	M3 (Asc)	M4 (Desc)		
Pa	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg	mmHg
5332.90	40	40.74	41.78	40.95	41.95	41.355	-1.355
7999.34	60	61.49	62.93	61.52	62.81	62.188	-2.188
10665.79	80	82.46	82.92	82.61	82.82	82.703	-2.703
13332.24	100	102.77	102.56	102.75	102.76	102.710	-2.710
15998.69	120	122.76	122.46	122.74	121.76	122.430	-2.430
21331.58	160	162.26	161.49	162.19	161.06	161.750	-1.750
26664.48	200	201.22	200.86	200.82	200.84	200.935	-0.935
33330.60	250	250.02	250.50	250.04	250.38	250.235	-0.235
39996.72	300	300.81	300.58	300.82	300.56	300.693	-0.692
			C				

After obtaining the results in the measurement process, the uncertainty in the sphygmomanometer calibration process is estimated by applying equations (3), (4), (5), (6), (7), (10), (12), and (13) to the data in table 6, table 7, table 8, and table 9. The estimated expanded uncertainty U_e for each measurement point is from 40 mmHg to 300 mmHg, expressed in the following tables.

Value	μ_A	$\mu_{B(Uncert.Res)}$	$\mu_{B(Uncert.His)}$	$\mu_{B(Pat.Acc)}$	$\mu_{B(Pat.Cal)}$	$\mu^2 c(E)$	V _{eff}	U _e
40	0.27	0.29	-0.27	0.11	0.031	0.49257	32.7370083	± 0.99
60	0.28	0.29	-0.27	0.11	0.031	0.49653	30.51918356	± 0.99
80	0.23	0.29	-0.22	0.11	0.031	0.44840	38.52510514	± 0.93
100	0.41	0.29	-0.41	0.11	0.031	0.65439	19.66285304	± 1.4
120	0.42	0.29	-0.42	0.11	0.031	0.67156	19.22435319	± 1.4
160	0.41	0.29	-0.42	0.11	0.031	0.66707	20.03117527	± 1.4
200	0.34	0.29	-0.35	0.11	0.031	0.57699	24.10064097	± 1.2
250	0.11	0.29	-0.12	0.11	0.031	0.34876	184.4206361	± 0.70
300	0.16	0.29	-0.17	0.11	0.031	0.38998	80.77529	± 0.79

Table 10. Results of the calibration of a sphygmomanometer 1

Source: own work

Table 6. Results of the calibration of a sphygmomanometer 2

Value	μ_A	$\mu_{B(Uncert.Res)}$	$\mu_{B(Uncert.His)}$	$\mu_{B(Pat.Acc)}$	$\mu_{B(Pat.Cal)}$	$\mu^2 c(E)$	V _{eff}	U _e
40	0.06	0.29	0.026	0.11	0.031	0.31733	260.6653836	± 0.64
60	0.03	0.29	-0.035	0.11	0.031	0.31450	273.494352	± 0.93
80	0.07	0.29	-0.078	0.11	0.031	0.32781	271.110429	± 0.66
100	0.05	0.29	-0.049	0.11	0.031	0.31905	274.8135412	± 0.64
120	0.13	0.29	0.014	0.11	0.031	0.33660	103.861981	± 0.68
160	0.10	0.29	-0.026	0.11	0.031	0.32660	179.3012176	± 0.66
200	0.11	0.29	-0.046	0.11	0.031	0.33200	156.2339085	± 0.67
250	0.05	0.29	-0.029	0.11	0.031	0.31640	267.2583553	± 0.64
300	0.04	0.29	0	0.11	0.031	0.31368	266.57264	± 0.63

Source: own work

Table 7. Results of the calibration of a sphygmomanometer 3

Value	μ_A	$\mu_{B(Uncert.Res)}$	$\mu_{B(Uncert.His)}$	$\mu_{B(Pat.Acc)}$	$\mu_{B(Pat.Cal)}$	$\mu^2 c(E)$	V _{eff}	U _e
40	0.07	0.29	0.06	0.11	0.031	0.32495	259.1393854	± 0.65
60	0.04	0.29	-0.04	0.11	0.031	0.31723	275.4984308	± 0.64
80	0.08	0.29	-0.08	0.11	0.031	0.33029	255.1699913	± 0.66
100	0.25	0.29	-0.25	0.11	0.031	0.47005	34.50213282	± 0.98
120	0.23	0.29	-0.23	0.11	0.031	0.44938	39.40032923	± 0.93
160	0.09	0.29	-0.08	0.11	0.031	0.33593	202.8159871	± 0.68
200	0.11	0.29	0.11	0.11	0.031	0.34995	162.5527822	± 0.71
250	0.01	0.29	-0.01	0.11	0.031	0.31149	265.051195	± 0.63
300	0.04	0.29	-0.06	0.11	0.031	0.31959	283.05484	± 0.64
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Value	μ_A	$\mu_{B(Uncert.Res)}$	$\mu_{B(Uncert.His)}$	$\mu_{B(Pat.Acc)}$	$\mu_{B(Pat.Cal)}$	$\mu^2 c(E)$	V _{eff}	U _e
40	0.40	0.29	-0.44	0.11	0.031	0.66789	23.64315036	± 1.4
60	0.33	0.29	-0.34	0.11	0.031	0.56469	25.46768298	± 1.2
80	0.31	0.29	-0.25	0.11	0.031	0.51013	20.39723568	± 1.1
100	0.35	0.29	-0.33	0.11	0.031	0.57123	21.31522725	± 1.2
120	0.28	0.29	-0.30	0.11	0.031	0.51404	32.33514734	± 1.1
160	0.34	0.29	-0.32	0.11	0.031	0.55941	22.33879556	± 1.2
200	0.32	0.29	-0.28	0.11	0.031	0.52676	22.33456091	± 1.1
250	0.16	0.29	-0.19	0.11	0.031	0.39968	91.22767152	± 0.81
300	0.24	0.29	-0.20	0.11	0.031	0.44295	33.63589	± 0.92
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Table 8. Re	esults of the	calibration	of a sph	nygmomanometer	4
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Source: own work



Figure 5. Contribution of uncertainty for each of the selected equipment

Each of the graphs with their respective analysis are detailed below.



Figure 6. Contribution of uncertainty, equipment 1



Table 10 and figure 6 are the sources of uncertainties that most contribute to the process. The uncertainty due to the sphygmomanometer's resolution predominates at 40 mmHg, 60 80 mmHg, 250 mmHg, and 300 mmHg. For the points 100 mmHg and 120 mmHg, the uncertainty that contributes the most is data repeatability and hysteresis for 160 mmHg and 200 mmHg. The uncertainty that contributes the most is due to the hysteresis of the sphygmomanometer.





In table 11 and figure 7, the sources of uncertainties that contribute the most to the process, where the uncertainty due to the sphygmomanometer's resolution predominates at all points.



Figure 8. Contribution of uncertainty, Team 3

Table 12 and figure 8 show the sources of uncertainties that contribute the most to the process, where the uncertainty due to the resolution of the sphygmomanometer prevails at all points.





Source: own work

Table 13 and figure 9 show the sources of uncertainties that contribute the most to the process, where the uncertainty due to the resolution of the sphygmomanometer predominates at the points 80 mmHg, 100 mmHg, 120 mmHg, 200 mmHg, 250 mmHg, and 300 mmHg, which correspond to most of the points. For the points 40 mmHg and 60 mmHg, and 160 mmHg, the uncertainty that contributes the most is data repeatability and hysteresis.

Discussion

According to the results obtained in each of the calibrations carried out, similar behavior is observed in the different instruments under test, in which the sources determined in the mathematical model highlight the different components. This allows us to get closer to the real behavior of the equipment and an assurance of its measurements.

Thus, in figure 10, it can be observed that for equipment 1, the predominant uncertainty in most of the points is the equipment's resolution, followed by repeatability and hysteresis, while for equipment 2 and 3, the uncertainty prevails due to the team resolution at all points. According to the above, it can be inferred that equipment 1 had a greater variation in the data obtained compared to 2 and 3 as they had greater stability in the behavior of the data since the repeatability and hysteresis uncertainty is lower at most points. Comparing the 3, it is observed that the team with the greatest stability in the data is equipment 2 since in equipment 3, the uncertainty due to repeatability and hysteresis is greater at the points 100 mmHg and 120 mmHg than at the rest of the points.



Figure 10. Comparison between equipment 1, 2 and 3

Source: own work

In figure 11, equipment 1, compared to equipment 4, presents a greater variation in the behavior of the data, since only in the last two points it does not present a high uncertainty due to repeatability and hysteresis. For equipment 4, it only occurs in the initial points and the two intermediate points. When comparing with the rest of equipment 4, it is observed that the uncertainty by team resolution predominates.





In figure 12, equipment 2 and 3 have a more stable behavior than equipment 4. The above is because the uncertainty by repeatability and hysteresis is lower in most of the points. For equipment 3, it is observed that at the points 100 mmHg and 120 mmHg, the uncertainty due to repeatability and hysteresis is greater than in the rest of the points.





According to the discussion carried out previously, the predominant uncertainty in most cases is by the resolution of the equipment, followed by the behavior of the equipment in the repeatability and hysteresis test.

Conclusions

This article estimates the uncertainty in the calibration of sphygmomanometers under OIML R16-1 from a legal metrology perspective. Identifying sources of uncertainty has not been perceived or analyzed in most of the research studies reported in the literature. The experimental results show that derived from the equipment specifications under test, the uncertainty that contributes the most to each of the calibrations is the resolution of the sphygmomanometer followed by the uncertainty due to repeatability or hysteresis, which is associated with the behavior of the equipment. The novelty factor of the proposed methodology consists in showing the advantage of estimating uncertainty through a structure that combines the mathematical model under a non-stochastic method according to the GUM with the international standard OIML R16 (which has gone through different reviews), which provides consistent execution activities aligned with the regulatory standard to be performed in the calibration of sphygmomanometers, with the additional possibility of expanding the scope to processes related to model approval. Likewise, the importance of ensuring the results in medical equipment, specifically in sphygmomanometers, within the framework of model approval processes and the impact that these activities can have on patient safety is highlighted.

The consistent results in the different equipment under test carried out allow its application to deliver pertinent information to the healthcare part for decision-making when calibrating sphygmomanometers as diagnostic equipment. Future work remains to carry out a multivariate analysis with different calibration methodologies that define the correlation between the different sources of uncertainty and statistically determine the values of errors and expanded uncertainty, independent of brands and models of sphygmomanometers.

Acknowledgment

This article was carried out within the framework of a research project called "Normative harmonization of legal metrology through a management model applied to the health sector in Colombia" with code P17202, funded by the Instituto Tecnológico Metropolitano ITM (Medellín-Colombia), and the data obtained were carried out in the ITM Metrology Laboratory, in the General Hospital of Medellín.

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